

# Jevo Brushless Type C Series (Current control type)

Model DLV45C



- Current controlled torque system
- Low-voltage brushless motor
- ESD (Electrostatic Discharge) protection structure
- For both hand-held / automated machines (External startup)
- Nine speed settings available
- Automatic three step speed control function
- Two types of measuring methods (Time/Motor rotation signal)
- Seven color indication LED (At the tip of the screwdriver)
- Two external I/O signal connection ports (NPN ⇔ PNP switchable, RS-232C)
- Various settings can be configured via a PC (Free setting software available on NITTO KOHKI website)
- Built-in screw counting function

















# Torque and fastening setting of

Ist unit

1.2 Nm 1000 min-1 2nd unit

1.8 Nm 500 min-1 3rd unit

3.0 Nm 800 min-1 4th unit

1.8 Nm 500 min<sup>-1</sup>

# delvo **Brushless Type** C Series (Current control type)







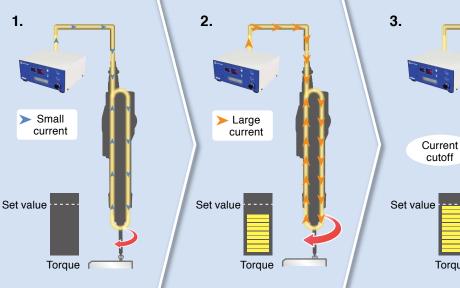












Mechanism of **Current Controlled Torque System** 

CH -

**FUNCTION** 

COUNT

# 1. Start of fastening

At start-up, a small amount of current is allowed.

# 2. During fastening

As the load increases during fastening, so does the amount of current allowed.

# 3. End of fastening

When the desired current value (adjusted by corresponding torque value) is reached, current flow is cut off and the screwdriver stops.

Torque

cutoff

# **Specifications**

| _           |               |                |                      |   |                  |
|-------------|---------------|----------------|----------------------|---|------------------|
|             | Model         |                | Bit                  | DLV45C12L-AY K  | DLV45C12P-AY K   |
| L           | Starting Met  | hod            |                      | Lever Start   | Push to Start    |
|             | Power Source  | ce             |                      | From dedica   | ted controller   |
|             | Torque Adju   | stment         |                      | From 1 to 100%  | in 1% increments |
|             | Torque        |                | (Nm [lbf·in])        | 0.6 to 4.5 [  | 5.3 to 39.8]     |
|             |               | SOFT fastening | (min <sup>-1</sup> ) | 400 to  | 1200             |
| L           | Free speed    | setting        | Speed Level          | Level   | 1 to 9           |
| Screwdriver | i icc specu   | HARD fastening | (min <sup>-1</sup> ) | 100 t   | o 700            |
| wdr         |               | setting        | Speed Level          | Automatically set by torque setting   |                  |
| cre         | Power Cons    | umption        | (W)                  | 44  |                  |
|             | Screw Size    | Machine Screw  | (mm)                 | 3.0 to 6.0  |                  |
| ctri        | Screw Size    | Tapping Screw  | (mm)                 | 2.5 t   | 0 5.0            |
| Electric    | Bit Type (mm) |                |                      | 23 9  | 6.35             |
|             | Mass          |                | (kg [lbs])           | 0.63 [1.39]   |                  |
|             | Standard Ac   | cessories      |                      | Bit NK35 (No.2×7×75): 1 pc.<br>Connection Cord 2 m (DLW9078): 1 pc.<br>Suspension Bail: 1 pc. |                  |

|            | Model                                       | DCC0241X-AZ   |  |
|------------|---|---|--|
|            | Input Voltage                               | 100 - 240 V AC, 50/60 Hz  |  |
|            | Output Voltage                              | 40 V DC   |  |
|            | Input Signal Method                         | Photocoupler input<br>(24 V DC drive (5 mA/1 input),<br>NPN/PNP switchable)             |  |
| Controller | Output Signal Method                        | Photocoupler output<br>(30 V DC or less, 80 mA/1 output or less,<br>NPN/PNP switchable) |  |
| ပိ         | Service Power Source                        | 24 V DC (Maximum capacity 200 mA)   |  |
|            | Serial Signal Method                        | RS-232C   |  |
|            | ESD (Electrostatic Discharge)<br>Protection | Adopted (IEC61340-5-1 compliant)  |  |
|            | Mass (kg [lbs])                             | 1.8 [3.97]  |  |

# Caution

- Speed and torque differs depending on the temperature. (Use within the range of + 10 to +40  $^{\circ}\text{C}$ )
- \*Do not retighten screws that are already tightened. The torque will become larger than the set torque.

- About optional accessories (See page 9 "Optional Accessories")

  \*The power cord for the controller (DCC0241X-AZ) is sold separately.

  Ask us for the required power cord when ordering.

  \*For torque measurements, please use Nitto Kohki's Torque Checker and Soft Joint / Hard Joint (sold separately).

# thirty screwdrivers

# can be consolidated into one.

**5th unit**3.0 Nm

1000 min<sup>-1</sup>

3.0 Nm 400 min<sup>-1</sup>





Two types of fastening mode available subject to the workpiece and fastening conditions. Coordinate the actual workpieces, screws and operating conditions and determine the fastening mode, torque range and rotation speed.

# **SOFT / HARD fastening Settings**

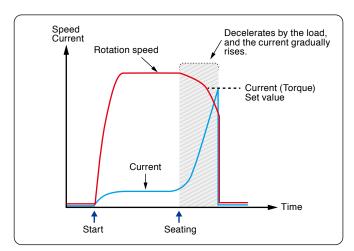
Instruction manual P68, P69

### **SOFT fastening setting**

Suitable for workpieces with high fastening load such as tapping screws or fastening soft objects such as rubber.

### Timing chart

The image of the control action, seating the screw at the set rotation speed.

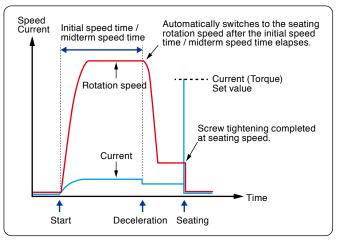


# **HARD** fastening setting

Suitable for workpieces with small fastening load such as threaded holes or rigid bodies such as metal.

# Timing chart

A control that seats the screw at the seating rotation speed according to the torque setting value, when the initial speed time / midterm speed time is elapsed.



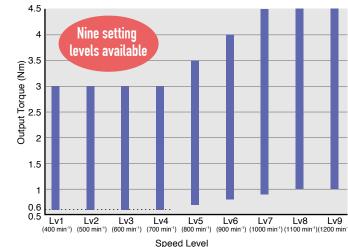
<sup>\*</sup>When measuring the torque with Torque Checker, use Soft Joint (DLW4050) for SOFT fastening setting, use Hard Joint (DLW4040) for HARD fastening setting. (See page 9)

# **Torque range: Output Torque and Rotation Speed**

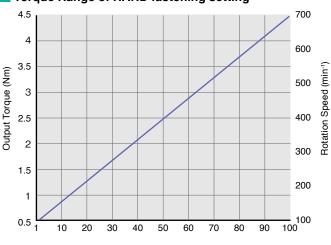
Instruction manual P11, P12

There are nine levels for rotation speed setting. (400 to 1200 min<sup>-1</sup>) Corresponds to high torque fastening, even at SOFT fastening setting or slow rotation speed. (Corresponds to a maximum of 3 Nm at 400 min<sup>-1</sup>)

# ■ Torque Range of SOFT fastening setting



### ■ Torque Range of HARD fastening setting



Torque setting (%)

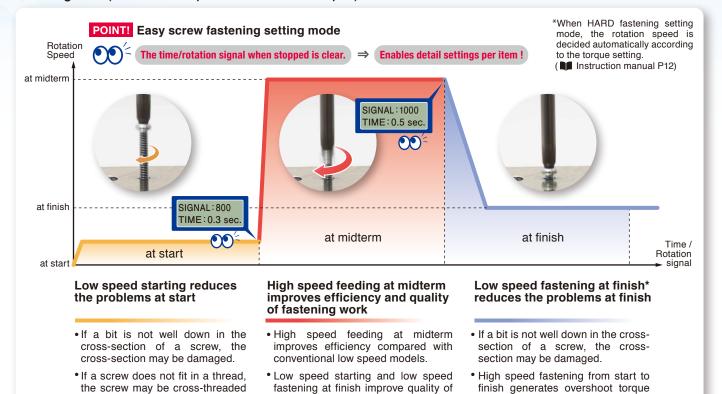
# Rotation speed: Built-in automatic speed control function

Instruction manual P30 to P32

Built-in automatic three step variable speed control function. Enables compatibility of "quality of slow speed" and "efficiency of high speed".

Low speed at start High speed feeding Low speed fastening

○ Timing chart (Below rotation speeds and times are examples)



screw fastening work compared with

conventional high speed models.

# **Screw fastening time measuring (Upper / Lower limit)**

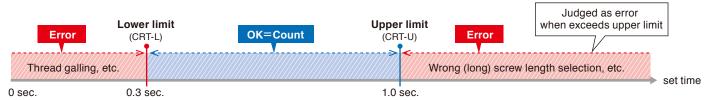
Instruction manual P32

(over-tightening by an inertial force)

and may cause breakage of a screw

neck part.

The upper / lower limit of screw fastening time (correct timer) can be set. It will be judged as "correct fastening" only when the measured time is between the upper limit and lower limit. Either limit can be switched off. (Below times are examples)



# Two types of measuring methods

and seated partially.

Instruction manual P41

There are two methods to measure the setting time of start and midterm.



### TIME

Measure by time. You can decide the setting value intuitively.



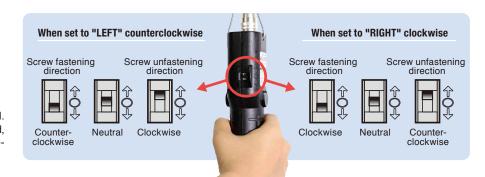
# **MOTOR SIGNAL**

Measure by the motor rotation signal. Even if you change the rotation speed, you do not need to set the measurement time or rotation time.

# **Rotation direction setting**

Instruction manual P37

Specify the rotation direction of forward rotation. "RIGHT" for clockwise, "LEFT" for counterclockwise.



# **Channel setting**

Instruction manual P4, P28, P70

The unit of fastening work performed continuously under the same conditions is called a "channel". Up to thirty channels can be registered in the memory.



# Example of motion setting

| Channel Motion setting             | CH1      | CH2     | СНЗ      | CH4      |   | CH30     |
|------------------------------------|----------|---------|----------|----------|---|----------|
| 1: Screw fastening mode            | SOFT     | SOFT    | HARD     | SOFT     |   | HARD     |
| 2: Number of screw fastening       | 2 pcs.   | 13 pcs. | 5 pcs.   | 3 pcs.   |   | 20 pcs.  |
| 3: Speed level at finish           | Lv5      | Lv9     | AUTO     | Lv1      |   | AUTO     |
| 4: Torque                          | 10%      | 80%     | 30%      | 45%      | • | 20%      |
| 5: Speed level at start            | Lv1      | OFF     | Lv9      | Lv3      |   | Lv1      |
| 6: Rotation time at start          | 0.1 sec. | _       | 0.3 sec. | 0.8 sec. | • | 1.0 sec. |
| 7: Speed level at midterm          | Lv9      | OFF     | OFF      | Lv8      |   | Lv7      |
| 8: Rotation time at midterm        | 0.5 sec. | _       | _        | 1.2 sec. | • | 0.5 sec. |
| 9: Speed level at reverse rotation | Lv9      | Lv9     | Lv7      | Lv5      |   | Lv5      |
| :                                  | :        | :       | :        | <u>:</u> | • | :        |
| 26: Rotation direction             | RIGHT    | RIGHT   | RIGHT    | LEFT     |   | RIGHT    |

# Channel pattern setting

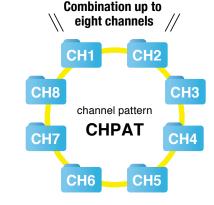
Instruction manual P4, P38, P70

A series of operations combining each channel is called a "channel pattern". Up to eight channels can be registered per channel pattern.

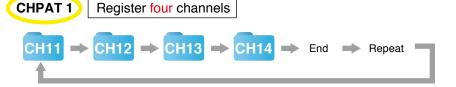
Up to thirty channel patterns can be set.

When combining nine or more channels, use multiple channel patterns.





# Example of channel pattern







Register ten channels





# **Setting lock function**

Instruction manual

Entry of password to enter channel setting mode can be enabled/disabled. Prevents unintended setting change.

# COM SETTING-SETTING LOCK:OFF

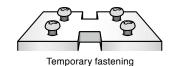
COM SETTING-SETTING LOCK: ON

flashing

# Auto reverse function

■■ Instruction manual P35

The screwdriver automatically reverses after torqueup or reaching the preset time. Auto reverse mode can be used for temporarily fastening screws or verifying tapped holes.



Verifying tapped holes

# Built-in LED function Instruction manual P19, P37

The LED at the tip of the electric screwdriver is always lit in the specified color. Color coding for each channel is possible.

Also, it lights in the specified color when OK(PASS) / NG(FAIL) / count up.





Controller

# Two safety functions

1. Caution mode Instruction manual P43

A torque value that alerts the operator can be set. After the channel is switched, if the torque exceeds the preset value, a warning is displayed on the counter and the electric screwdriver will not start.





Flashes in yellow

# 2. Refastening prohibited time setting Instruction manual P36

To prevent additional fastening (second tightening, confirmation tightening, etc.), it can be set so that it does not restart after torque-up (for 0.0 to 9.9 seconds).

Adjust the set value according to the skill level of the operator and the interval between screw fastening operations.





Controller Flashes in red

# External I/O signal

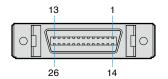
When connecting to an external device, it can be connected in two ways.

## 1. External I/O Cable

Instruction manual P47 to P52

Use External I/O Cable DLW9091. Compatible with both NPN/PNP.

It can be wired according to the externally connected equipment.



Connector: IEEE1284 half pitch connector (26-pin)

| Terminal No. | Function                      | Details  | I/O     |
|--------------|-------------------------------|--|---------|
| 1            | +24 V DC                      | Built-in service power supply (Capacity: Maximum 200 mA)   | Service |
| 2            | 0 V DC                        | Built-iii service power suppry (Capacity, Maximum 200 ma)  | supply  |
| 3            | Input signal common terminal  | Input signal common terminal (See page 49 of instruction manual)   | Input   |
| 4            | Output signal common terminal | Output signal common terminal (See page 50 of instruction manual)  | Output  |
| 5            | Switching signal A            |  |         |
| 6            | Switching signal B            |  |         |
| 7            | Switching signal C            | Specify channel or channel pattern using a 5-bit input signal.   |         |
| 8            | Switching signal D            |  |         |
| 9            | Switching signal E            |  | Input   |
| 10           | Forward rotation start        | Startup with external input signal.  |         |
| 11           | Reverse rotation start        | The electric screwdriver operates while the input signal is ON.  |         |
| 12           | Workpiece                     | Input workpiece signal (workpiece detection signal output). Workpiece signal is ON while input signal is ON. |         |
| 13           | External reset                | Input external reset signal  |         |
| 14           | N/A                           | No connection  | _       |
| 15           | Channel A                     |  |         |
| 16           | Channel B                     |  |         |
| 17           | Channel C                     | The channel being operated or being set is ON  |         |
| 18           | Channel D                     |  |         |
| 19           | Channel E                     |  |         |
| 20           | Forward rotation signal       | Output signal is ON during forward rotation  |         |
| 21           | Reverse rotation signal       | Output signal is ON during reverse rotation  | Output  |
| 22           | Operation OK                  | Output signal is ON when the screw fastening of the set count is complete and judged as operation OK (PASS). |         |
| 23           | Count up                      | Output signal ON for 0.3 seconds when screw fastening is normal (at torque-up).                              |         |
| 24           | Operation NG                  | Output signal ON when workpiece signal is OFF during operation and judged as operation NG (FAIL).            |         |
| 25           | Screw fastening NG            | Output signal ON for 0.3 seconds when screw fastening is NG (FAIL).  |         |
| 26           | N/A                           | No connection  |         |

# 2. RS-232C

### Instruction manual P55 to P58

**Use Communication Cable** (Straight-through) DLW9092 to connect with PCs or sequencers (PLC).

|                    | Transmission method       | Asynchronous (asynchronous communication) |  |  |  |
|--------------------|---------------------------|---|--|--|--|
| Communication line |                           | Full duplex                               |  |  |  |
| Transmission speed |                           | 38400 bps                                 |  |  |  |
| Number of data     |                           | 8   |  |  |  |
| Parity             |                           | None                                      |  |  |  |
| Stop bit           |                           | 1   |  |  |  |
| Handshake          |                           | None                                      |  |  |  |
|                    | Delimiter                 | Receive: CR+LF (¥r¥n)                     |  |  |  |
|                    | (communication separator) | Send: CR+LF (¥r¥n)                        |  |  |  |

| Pin No. | Signal name | I/O                |
|---------|-------------|--------------------|
| 2       | TxD         | OUT (This tool⇒PC) |
| 3       | RxD         | IN (PC⇒This tool)  |
| 5       | GND         | GND                |
|         |             |                    |

\*Other pins are not used

| Ę | 5    | 1     |
|---|------|-------|
|   | 0000 |       |
|   | 9 6  | <br>} |

Connector pin layout (D-SUB 9-pin (female))

### ♦ Send / receive commands

♦ Specifications (RS-232C)

| Operation                              | Send command             | Response from controller  |
|--|--------------------------|---|
| Forward rotation drive                 | FWD¥r¥n                  | FWD¥r¥n   |
| Reverse rotation drive                 | RVS¥r¥n                  | RVS¥r¥n   |
| Drive stop                             | STP¥r¥n                  | STP¥r¥n   |
| Switching channel / channel pattern *1 | MOV:p¥r¥n<br>(p=1 to 30) | At channel switching CH :p¥r¥n At channel pattern switching CHP:p¥r¥n |
| Screw count reset                      | CRT¥r¥n                  | CRT¥r¥n   |
| Workpiece reset                        | WRT¥r¥n                  | WRT¥r¥n   |
| Workpiece signal ON                    | WIN¥r¥n                  | WIN¥r¥n   |
| Workpiece signal OFF                   | WOT¥r¥n                  | WOT¥r¥n   |
| Resend request *2                      | RSD:p¥r¥n<br>(p=1 to 10) | Command sent nth time before, specified by the parameter value        |

<sup>\*1</sup> The switching target differs depending on the setting of the common setting "Channel change type" (CH CHANGE).

[Example] Send command "RSD:3\forall r\forall n"  $\to$  Returns the command sent by the controller three times before.

Since control is performed even when communication between the controller and PC or sequencer fails, use this function when you wish to maintain the reliability of transmission and reception. This command transmission is not included in the ten commands that are stored.

# Notification command

In addition to RS-232C signals, commands are sent from the controller to the PC or sequencer(PLC) when processing is performed manually or by contact signals.

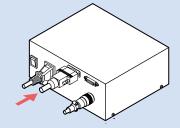
| Operation  | Notification from controller |
|--|------------------------------|
| At forward rotation drive start  | FWD¥r¥n                      |
| At reverse rotation drive start  | RVS¥r¥n                      |
| At drive stop completion   | STP¥r¥n                      |
| Operation OK (PASS) notification   | OK ¥r¥n                      |
| Workpiece signal ON  | WIN¥r¥n                      |
| Workpiece signal OFF   | WOT¥r¥n                      |
| Count up (screw fastening completes normally) notification   | CUP:p¥r¥n                    |
| p = Measured fastening time or signal is output  | (p=1 to 60000)               |
| Operation NG (workpiece out while fastening count remaining) notification  | WNG¥r¥n                      |
| Screw fastening NG (FAIL) notification<br>p1=Screw fastening NG (FAIL) No.<br>p2=Measured fastening time or signal is output | FNG:p1:p2¥r¥n                |
| At channel switching   | CH :p¥r¥n<br>(p=1 to 30)     |
| At channel pattern switching   | CHP:p¥r¥n<br>(p=1 to 30)     |
| When a non-supported command or parameter is input   | CER¥r¥n                      |

# 1. External I/O Cable DLW9091

Insert the separately sold External I/O Cable DLW9091 to the external signal connector to connect between the terminal and wiring.

### 2. RS-232C





Insert the separately sold Communication Cable (Straight-through) DLW9092 to the RS-232C connector to connect to a PC or sequencer (PLC).

When the channel pattern is switched, the channel is also switched, so the responses are sent continuously.

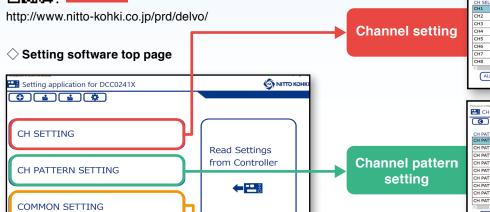
<sup>\*2</sup> Up to the latest ten commands sent from the controller to the PC or sequencer are stored. When signals could not be received correctly due to noise or some other reason, the command of nth time before, specified by the parameter will be sent from the PC or sequencer.

# Easy setting with dedicated software

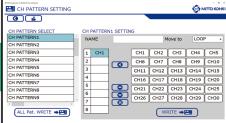
Channels and Channel patterns can be easily set with dedicated software. Download free from our website.











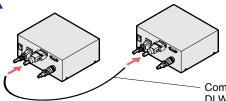


# **Setting data transmission function** between controllers

# Instruction manual P45

The channel and channel pattern settings can be transmitted to another controller.

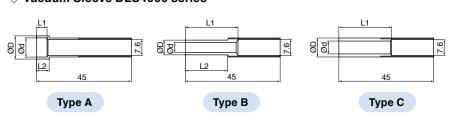
This is very convenient when the same work is divided into multiple processes.



Communication Cable (Crossover) DLW9093

# Vacuum Sleeves and applicable Bits

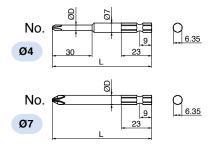
# ♦ Vacuum Sleeve DLS4000 series



| Model      | Ød   | ØD   | L1  | L2 | Length | Applicable Bit *2 | Shape (Type) | Part No. |
|------------|------|------|-----|----|--------|-------------------|--------------|----------|
| DLS4220    | 9.1  | 11   | 5   | 6  |        | No.2x7x75         | Α            | TD08001  |
| DLS4221    | 10.6 | 12.5 | 5.5 | 7  |        | No.2x7x75         | Α            | TD08002  |
| DLS4222 *1 | 8    | 11   | 5.3 | 22 |        | _                 | Α            | TD07850  |
| DLS4223 *1 | 8.2  | 10   | 5   | 6  |        | No.2x7x75         | Α            | TD07851  |
| DLS4224 *1 | 6.8  | 9    | 25  | _  | 4.5    | _                 | С            | TD07852  |
| DLS4225    | 4.6  | 7    | 25  | 20 | 45     | No.1x4x75         | В            | TD09344  |
| DLS4226    | 5.1  | 7    | 25  | 20 |        | No.1x4x75         | В            | TD09617  |
| DLS4227    | 5.6  | 7    | 25  | 20 |        | No.2x4x75         | В            | TD09345  |
| DLS4228    | 6.1  | 9    | 25  | _  |        | No.2x4x75         | С            | TD09618  |
| DLS4229    | 6.4  | 9    | 25  | _  |        | No.2x4x75         | С            | TD09619  |
| DLS4230    | 7.1  | 9    | 25  | _  |        | No.2x4x75         | С            | TD09620  |

# \*1) Made-to-order product \*2) Select the correct size number that fits your screw head

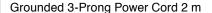
### 



| No. | ØD | L  | Part No. |
|-----|----|----|----------|
|     | 4  | 75 | TD20306  |
| 1   | 7  | 50 | TD20308  |
|     | 7  | 75 | TD20309  |
|     | 4  | 50 | TD20316  |
| 2   | 4  | 75 | TD20317  |
| 2   | 7  | 50 | TD20319  |
|     | 7  | 75 | TD20320  |
|     | 7  | 50 | TD20327  |
| 3   | 7  | 75 | TD20328  |
|     |    |    |          |

<sup>\*</sup> See delvo general catalog for other bit types.

# **Optional Accessories**



DLW9220 North America



DLW9240 Europe



DLW9250 UK



Diamond Shape Flange Coupling DLW9017



For mounting on automated screw fastening machines

Flange Coupling DLW9019



For mounting on automated screw fastening machines

Screw Vacuum Pump DLP2540 (115 V AC), DLP2570 (230 V AC)



Connect the tube to the vacuum pickup port. The vacuum will pick up the screw.

Vacuum Pickup DLP7401-K



For screw vacuum pickup

Vacuum Sleeve DLS4000 series



Select according to the screw shape

Torque Checker DLT1673A



For torque control of screwdrivers

Soft Joint DLW4050





The bit for measuring is included. (NK35BN 13×19×10×75)

For SOFT fastening torque measurement

Hard Joint DLW4040





The bit for measuring is not included. (NK35BN 13×19×10×75)

For HARD fastening torque measurement

External I/O Cable 3 m DLW9091



Connect when using external signals

Communication Cable 3 m (Straight-through) DLW9092



Connect to PCs and PLCs (sequencers) when using external signals

Communication Cable 3 m (Crossover) DLW9093



Connect controllers to transmit settings

Extension Cord 3 m DLW9310



Extends cord length between controller and screwdriver

Connection Cord 2 m DLW9078



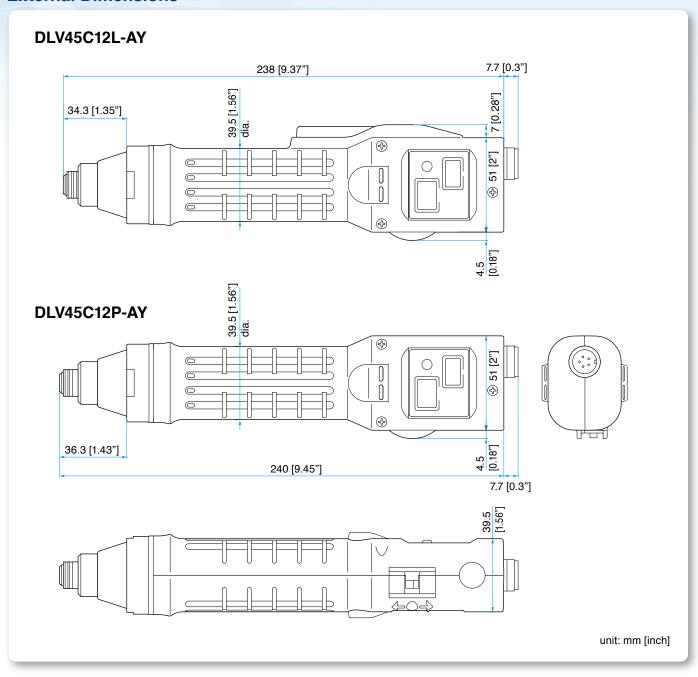
Connects controller and screwdriver

Pistol Grip DLW2300ESD

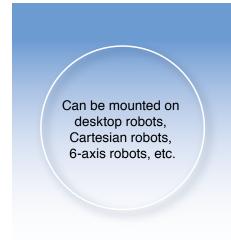


For operator fatigue reduction, suitable for horizontal fastening

# **External Dimensions**



# Example of installation on automated machines

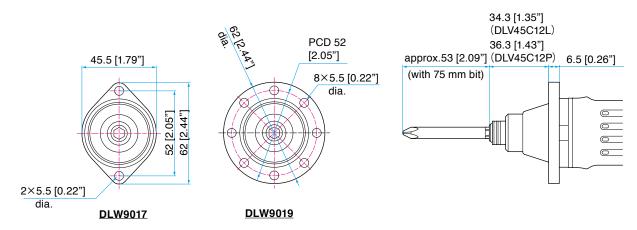






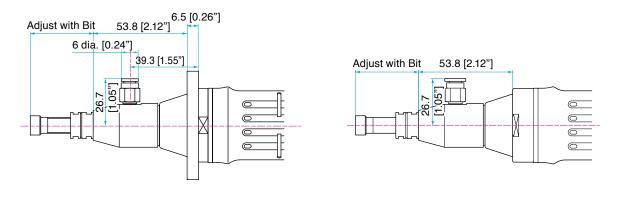
# **External Dimensions**

# When Flange Coupling DLW9017/DLW9019 is mounted

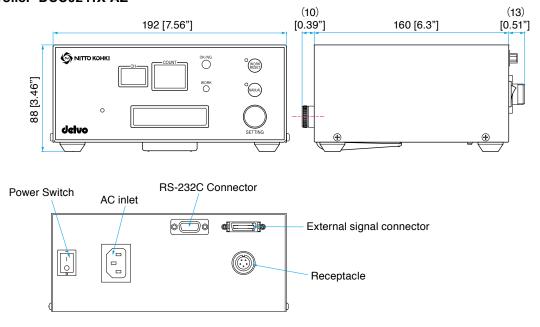


# When Flange Coupling and Vacuum Pickup DLP7401-K is mounted

# When Vacuum Pickup DLP7401-K is mounted



## Controller DCC0241X-AZ



unit: mm [inch]



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